

6224

Requires a version of Windows ®



Windows 7 (32 or 64-bit)
Windows Vista (32 or 64-bit)
Windows XP SP2 (32-bit)
Windows 2000 SP4

12 Channel • 24-Bit • Half/Full-Bridge Analog Input • Ethernet



High-speed, Strain Gauge Input Module



372738C-01

Rev 1.2

Measurement Computing

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Warranty Information

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Refer all service to qualified personnel. This caution symbol warns of possible personal injury or equipment damage under noted conditions. Follow all safety standards of professional practice and the recommendations in this manual. Using this equipment in ways other than described in this manual can present serious safety hazards or cause equipment damage.



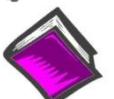
This warning symbol is used in this manual or on the equipment to warn of possible injury or death from electrical shock under noted conditions.



This ESD caution symbol urges proper handling of equipment or components sensitive to damage from electrostatic discharge. Proper handling guidelines include the use of grounded anti-static mats and wrist straps, ESD-protective bags and cartons, and related procedures.



This symbol indicates the message is important, but is not of a Warning or Caution category. These notes can be of great benefit to the user, and should be read.



In this manual, the book symbol always precedes the words "Reference Note." This type of note identifies the location of additional information that may prove helpful. References may be made to other chapters or other documentation.



Tips provide advice that may save time during a procedure, or help to clarify an issue. Tips may include additional reference.

Specifications and Calibration

Specifications are subject to change without notice. Significant changes will be addressed in an addendum or revision to the manual. As applicable, the hardware is calibrated to published specifications. Periodic hardware calibration is not covered under the warranty and must be performed by qualified personnel as specified in this manual. Improper calibration procedures may void the warranty.

CAUTION



Using this equipment in ways other than described in this manual can cause personal injury or equipment damage. Before setting up and using your equipment, you should read *all* documentation that covers your system. Pay special attention to Warnings and Cautions.

Note:

During software installation, Adobe® PDF versions of user manuals will automatically install onto your hard drive as a part of product support. The default location is in the **Programs** group, which can be accessed from the *Windows Desktop*. Initial navigation is as follows:

Start [on Desktop] ⇒ All Programs ⇒ IOtech ...

Refer to the PDF documentation for information regarding hardware and software.

For detailed information regarding Encore software, refer to the Help information that can be accessed directly from IOtech's Encore application following its installation.

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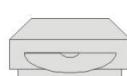
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¹ For information regarding digital circuitry, refer to the *Digital I/O* section of the *Specifications* chapter.

High-speed, Strain Gauge Input Module

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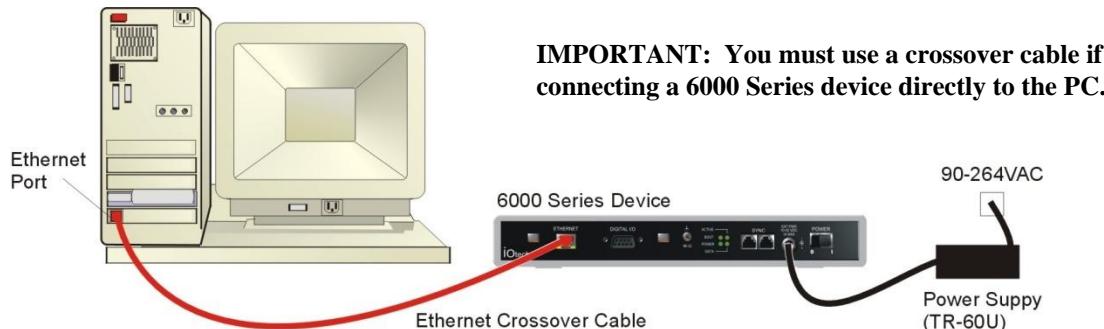


Before you get started verify that you have the following items and meet or exceed the minimum requirements listed.

- IOtech 6224
- TR-60U Power Supply and Cable
- Ethernet Crossover Cable*
- *IOtech Encore Installation CD*
- PC: Minimum Requirements:
CPU: Intel® Pentium® 4, 3.0 GHz or equivalent
RAM: 1 GB
Monitor: 1024 by 768 screen resolution
- PC: Recommended:
CPU: Intel® Core™ 2 Duo Family
RAM: 2+ GB
Monitor: 1024 by 768 screen resolution

*An Ethernet crossover cable (provided) should only be used when connecting a 6000 Series device directly to the PC. A standard Ethernet cable should be used when connecting via a hub/switch. A Gigabit switch is recommended when connecting multiple devices.

Step 1 - Connect the 6224 to the Ethernet and to the Power Supply



In this scenario the 6224 is connected directly to an Ethernet port on a host computer.

1. Connect the Ethernet cable to the Ethernet jack on the 6224. **If connecting directly to the PC, as indicated above (i.e., instead of connecting to a network hub) you must use an Ethernet crossover cable.**
2. Connect the other end of the Ethernet cable to the Ethernet jack on the host computer or network hub.
3. Connect the power supply cable from the TR-60U Power Supply to the External Power connector on the 6224.
4. Connect the TR-60U to a standard AC outlet; and set the rear panel Power Switch to “I” to turn the unit on. The 6224 Power LED will light up.
5. If Encore software is already installed, reboot the PC and skip to Step 2; otherwise proceed to Step 2, *Install Encore Software*.

Step 2 – Install Encore Software

1. Close all running applications on the host PC.
2. Insert the *Encore CD* into your CD-ROM drive and wait for the CD to auto-run.
An *Opening Screen* will appear. If AutoRun is disabled: (a) right-click Windows Start menu, (b) select *Explore*, (c) navigate to the CD ROM drive, and (d) double-click *Autorun.exe*
3. Follow the screen prompts.

Step 3 – Use Encore to Configure the 6224

1. Run the Encore software application (**Start>>All Programs>>IOtech>>Encore**).
2. In Encore's main toolbar, click the **Hardware Configuration** button. The **Hardware Configuration** window will open.
3. Select your device from the **Detected Devices** panel.
4. Click the top arrow button to set your device as a **Project Device**.
5. In Encore's **Hardware Configuration** window, look in the **Device Information** panel to verify that your 6224 has an **IP Address**. Note the following points regarding common connection scenarios. Both points assume that you have not changed the 6224 from its default setting of **Obtain an IP Address Automatically**.
 - **Direct Connect** – When a 6000 Series device is connected directly (via crossover cable or hub/switch) to a host PC with no fixed IP Address, you will need to reboot the PC and the device to allow a default IP Address to be set. This setting of an IP Address is automatic. No other action is needed. (See note.)
 - **Network Connect (Common scenario using existing network with DHCP server)** – A 6000 Series device will automatically request and receive an IP Address. No user action is needed. (See note.)
- Note** - Encore will provide a message to indicate an IP Address problem if one exists. If you receive such a message, consult your network administrator and also check Encore's *Comprehensive Help* file (via the **Help** pull-down menu on Encore's main window). Look at the topic: *Connection Scenarios and IP Addresses* (under *Configuring Hardware >>Hardware Setup*).
6. Click the **Next** button (at the bottom of the **Hardware Configuration** dialog) to access the **Acquisition Setup** tab.
7. Configure and enable channels as desired for your application. For detailed information refer to Encore's *Comprehensive Help* file (via the **Help** pull-down menu on Encore's main window).



Make sure that each computer and each device on the dedicated network has a unique IP address.

Step 4 - Connect Signal Lines

CAUTION



Turn off power to the system devices and externally connected equipment before connecting cables. Electric shock or damage to equipment can result even under low-voltage conditions.

Take ESD precautions (packaging, proper handling, grounded wrist strap, etc.)

The 6224 uses 10-pin RJ50 jacks for strain connection. Do not connect RJ45 plugs to these RJ50 jacks. Using RJ45 plugs can cause permanent damage to RJ50 pins 1 and 10, thus disabling shunt calibration.

The 6224 has 12 analog channel inputs (CH1 through CH12) via front panel RJ50 jacks and 8 digital I/O lines via rear panel DB9 connector.

Prior to making signal connections review the *Specifications* chapter of your 6224 user's manual to ensure that the input signals do not exceed the specified limits. After you have installed Encore you can access the pdf manual by navigating from the host PC's Windows Start Menu as follows (location shown is the default):

Start>>All Programs>>IOtech>>6000 Series>>6224 User Manual

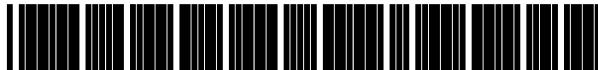


Reference Note: The Encore software application includes *Context-sensitive Help*, *Comprehensive Help*, a *Quick Start Video Tutorial*, and a *Getting Started* pdf.

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Introduction

The 6224 is a twelve-channel, 24-bit resolution strain measurement device that connects to a host PC's Ethernet port. The device is used to measure half-bridge and full-bridge sensors and can be synchronized with other 6000 series devices.

The hardware provides the signal conditioning and acquisition engine, while the software defines the specific configuration and analysis aspects of the system.

Note that the software includes both a *context sensitive* Help and a *comprehensive* Help file.

6224 Basic profile:

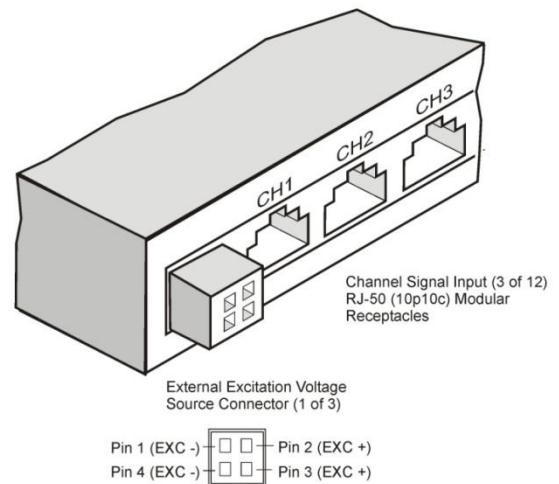
Model	Interface	Analog Input Channels	SYNC Ports	Analog Output Channels	Digital I/O	TEDS Support	Supported Bridges (Note 3)
6224	10/100BaseT Ethernet	12 Strain RJ50 Jacks	2	0	1 port/ 8 lines	(Note 2)	Quarter-Bridge I Quarter-Bridge II Half-Bridge I Half-Bridge II Full-Bridge I Full-Bridge II Full-Bridge III

Front Panel

The front panel houses twelve channel signal input jacks and three excitation voltage source connectors, one for each set of four channels.

The input channel jacks are type RJ50 (10p10c) and are labeled CH1 through CH12. The 10-connector pinout for the RJ50 connectors is included in chapter 3.

Optional external voltage source connectors are available. For additional information see the *External Excitation Voltage Sources* section of chapter 3.



Do not connect an RJ45 plug to an RJ50 jack. Using RJ45 plugs can cause permanent damage to RJ50 pins 1 and 10, thus disabling shunt calibration.

¹ For information regarding digital circuitry, refer to the *Digital I/O* section of the *Specifications* chapter.

² TEDS is supported by the 6224, but only if TEDS is supported by the software application.

³ For information regarding the various bridge types, refer to chapter 7.

Rear Panel

The following items reside on the rear panel; from left to right: 1st cable tie mount, Ethernet jack, DB9-Digital I/O port, 2nd cable tie mount, #6-32 chassis ground screw, four status LEDs, two synchronization jacks, a power input jack, and a power switch. A description of each follows.



CABLE TIE MOUNTS: Two cable tie mounts are present to provide for strain relief of cables.

ETHERNET: The 10/100BaseT Ethernet port can connect to the Ethernet port of the host PC, or to an Ethernet network. The Ethernet connector has two built in LEDs that indicate traffic flow on the network. Refer to *Accessories* in the *Specifications* chapter for Ethernet cables available from Measurement Computing.



When connecting the unit directly to a PC (i.e., when not connecting to a network hub) you will need to use an Ethernet crossover cable.

Ethernet cable length must be <3 m (9.8 ft) in order for the system to be CE Compliant.

DIGITAL I/O: Eight digital I/O lines are accessible via a 9-pin, female DSub connector. For details, refer to the *Digital I/O* section of the *Specifications* chapter.

GROUND (#6-32): Provides a connection point for Chassis Ground via use of a #6-32 machine screw.

STATUS LEDS:

- | | |
|---------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Power | 'ON' when the device is connected to a sufficient power source and the power switch is in the '1' (On) position. |
| Boot | During initial power up, the Boot light will be On to signal the first stage boot process. When this has completed successfully, the Boot light will remain Off. If an internal error is detected during this first stage boot process, this light will be blinking. Contact Measurement Computing to arrange repair service. |
| Active | During initial power up, the Active light will be Off during the boot process, including network configuration. The process will complete with a fast Blink, and then steady On condition. With both the Power and Active lights On, the device is in the Ready state. After this, the Active light will signal communications with a host computer at a slower blink rate. |
| Data | The Data light will be On any time the device is acquiring channel data that is available to the host PC control software. |

Note: After turning on the device, it can take up to 2 minutes to reach ready state, depending on network settings. This can be monitored by the LED sequence:
Power Light On → Boot Light On then Off → Active Light Off, then Blinking, then On.

SYNC: Two “synchronization ports” provide a means of synchronizing units regard to pre-trigger data and post-trigger scanning. Note that each 6000 Series device is capable of being designated as a Master Unit, Slave Unit, or Terminating Slave Unit. The assignment is made in Encore. Refer to the following section, *Synchronization*, for details. Refer to *Accessories* in the *Specifications* chapter for SYNC cables available from Measurement Computing.



Up to nine units can be synchronized. The total combined length of the SYNC cables is not to exceed 2.438m (8 ft).

POWER INPUT: +19 VDC to +30 VDC, through a connector on the chassis. Power is typically supplied to the device via a TR-60U, 24VDC universal power supply.

POWER SWITCH: A switch with a “0” label for Power Off, and a “1” for Power On.

Analog Circuitry

The 6224 is isolated from earth ground. However, the individual channels, within their four-channel group, are not isolated from each other. The EX+, EX-, and T- signals are common among the four channels in their group as indicated by note 1 on page 3-1 and in the block diagram (page 2-1).

You can connect the 6224 to a device that is biased at any voltage within the unit's rejection range of earth ground. The *Specifications* chapter includes additional information.

If you connect floating signals to the 6224, connecting the EX- signal to the earth ground or shield will result in better noise rejection.

Each of the twelve analog channels has its own 24-bit ADC and input amplifier. This allows you to simultaneously sample signals from all twelve channels.

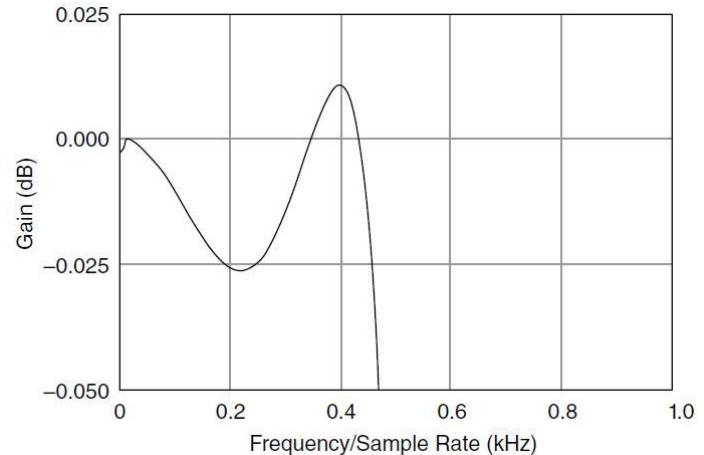
The 6224 includes anti-aliasing filters. Filtering is based on the sampling rate.

Filtering

The 6224 uses a combination of analog and digital filtering to provide an accurate representation of desirable signals while rejecting out-of-band signals. The filters discriminate between signals based on the frequency range, or bandwidth, of the signal. The three important bandwidths to consider are the passband, the stopband, and the alias-free bandwidth.

The 6224 represents signals within the passband as quantified primarily by passband flatness and phase nonlinearity. The filters reject frequencies within the stopband as quantified by stopband rejection. All signals that appear in the alias-free bandwidth are either unaliased signals or signals that have been filtered by at least the amount of the stopband rejection.

- **Passband** - The signals within the passband have frequency-dependent gain or attenuation. The small amount of variation in gain with frequency is called the passband flatness. The filters of the 6224 adjust the frequency range of the passband to match the data rate. Therefore, the amount of gain or attenuation at a given frequency depends on the data rate. The following figure shows typical passband flatness for a range of data rates.
- **Stopband** - The filter significantly attenuates all signals above the stopband frequency. The primary goal of the filter is to prevent aliasing. Therefore, the stopband frequency scales precisely with the data rate. Stopband rejection is the minimum amount of attenuation applied by the filter to all signals with frequencies that would be aliased into the alias-free bandwidth.
- **Alias-Free Bandwidth** - Any signal that appears in the alias-free bandwidth of the 6224 is not an aliased artifact of signals at a higher frequency. The alias-free bandwidth is defined by the ability of the filter to reject frequencies above the stopband frequency and equals the data rate minus the stopband frequency.



Synchronization

To synchronize from two to nine 6000 Series devices, link them together with synchronization cables as indicated in the example figure. Note that the first device (relative to the circuit) will be the **Master**. The last device connected will be the **Terminating Slave**. Thus the synchronized devices must proceed sequentially from the Master to Terminating Slave, as indicated in the figures. Note that *channel-to-channel* phase relationships in a multi-device configuration are not necessarily fixed. See notes below.

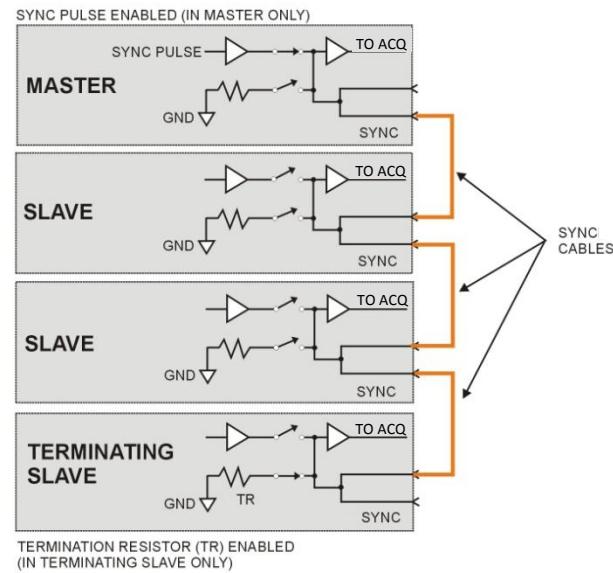


After physically linking the devices via the sync cables, they must still be configured as a “Synchronized Device Group” in the Encore software. To do this, use the **Synchronize Devices** page of Encore’s **Hardware Setup** tab.

Each Synchronized Group consists of one Master Device and at least one Slave Device. By default, the first 6000 Series device added to the Synchronization Group will be the Master and the last device added to the group will be the Terminating Slave.

Encore’s **Synchronized Device Group Configuration** panel includes a pull-down list which allows you to select the device that you want to have function as **Master** and the one you want to function as **Terminating Slave**, should this be different than the default settings.

Encore will display a *Synchronization Error* icon if it detects that a necessary synch cable is missing or not properly connected.



Up to nine units can be synchronized. The total combined length of the SYNC cables is not to exceed 2.438m (8 ft).

Unplug sync cables from devices that are not intended to be part of a “Synchronized Device Group.” Leaving a sync cable connected to an independent device can lead to errors.

Leaving an un-terminated sync cable on a synchronized device can lead to errors.

The sampled data phase relationship among channels between multiple devices is dependent on the Channel Sync Skew specification for each device. When utilizing different models in a multi-device system, any differences in the ADC filter delay (“Input Delay”) should be added.



Reference Note: For detailed information refer to the Encore software’s *Comprehensive Help*.

You can access the Help from within Encore. After doing so, navigate to the synchronization related topic as follows from the Help’s Contents panel:

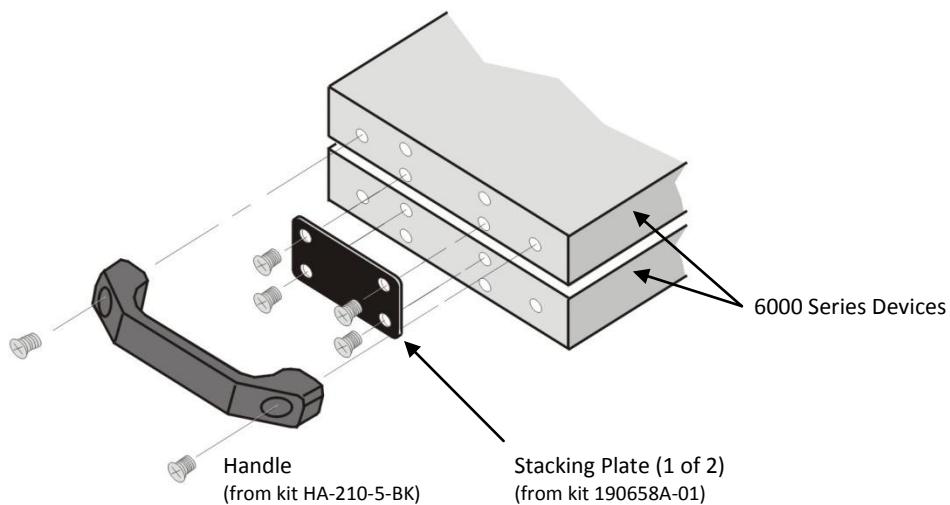
Configuring Hardware>>Hardware Setup>>Synchronizing Devices.

Stacking Plate and Handle Options

6000 Series device chassis are equipped with feet (on the lower panel) and dimples (on the upper panel) to allow for quick stacking of units.

A rigid securing of two or more units together is possible with the use of optional stacking plate kits (190658A-01). Each kit contains two stacking plates and eight screws (8-32 x .500 in., Phillips Flat, 82 Degree). If needed, additional kits can be used to stack and secure more devices.

An optional handle kit (HA-210-5-BK) is available to provide a convenient way of carrying a single 6000 Series device or a secured stacked set of devices. Each handle kit includes one black molded plastic handle and two mounting screws (1/4-20 x 7/8 in., Phillips Pan Head).



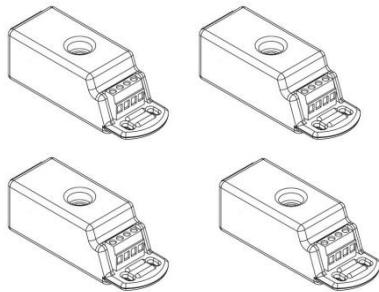
To attach two or more 6000 Series devices to each other using stacking plates:

1. Align the bottom two holes of a plate (hole tapers facing out) with the top two center holes of the lower 6000 Series device.
2. Secure the plate with two 8-32 x .500 in. Phillips screws (provided). Tighten the screws snug, but do not over-tighten.
3. Repeat steps 1 and 2 for the second plate, on the other side of the 6000 Series device.
4. Attach the second 6000 Series device using the remaining four screws.
5. Repeat these steps with other stacking plate kits and devices as applicable.

To mount a handle:

Attach the handle to a 6000 Series device using the two outer holes on the device and the two 1/4-20 x 7/8 in., Phillips Pan Head screws (provided). Tighten the screws snug, but do not over-tighten.

Quarter-Bridge Completion Accessories (CN-269 & CN-270)



The CN-269 and CN-270 are Quarter-Bridge Completion kits, with each kit consisting of four components. A single component (each member of its respective four-pack) can be used to add a Quarter-Bridge completion resistor to a channel on the 6224.

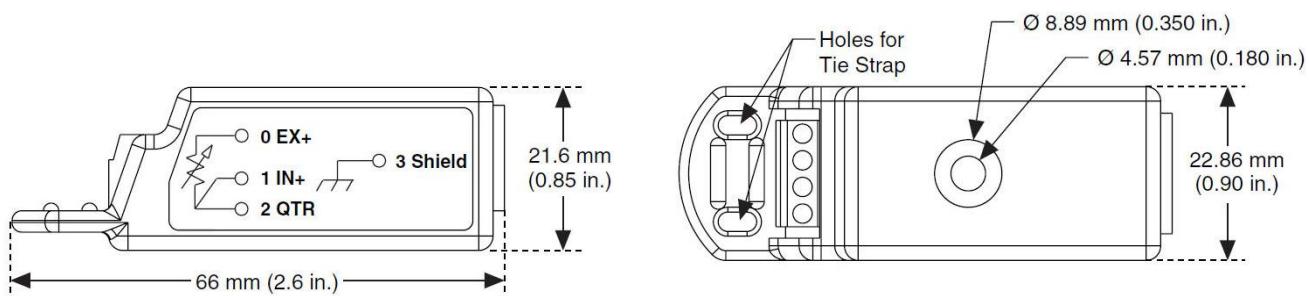
The CN-269 components each house a 120 ohm resistor.

The CN-270 components each house a 350 ohm resistor.

You will need an RJ50 M/M cable to use any of the Quarter-Bridge components with an 6224. Measurement Computing offers a pack of four RJ50 M/M, 1 meter (3.28ft) cables (see upcoming *RJ50 Cables* section).

As indicated in the right-hand figure below, CN-269 and CN-270 components each have two holes that can be used to loop a plastic tie-strap through, as a means of adding strain relief for the wire connections to the screw terminals.

If you want to mount a component, use a M4x20 screw (or similar hardware) that can fit into the 8.89 mm (0.350 in.) outer clearance/4.57 mm (0.180 in.) inner clearance hole. See figure.



Specifications

(typical for the range -40 to 70 °C)

Weight 32 g (1.1oz) per single component

Operating temperature -40 to 70 °C

Resistor values:

CN-269 120 Ω

CN-270 350 Ω

Resistance drift:

CN-269 0.012 Ω/°C

CN-270 0.035 Ω/°C

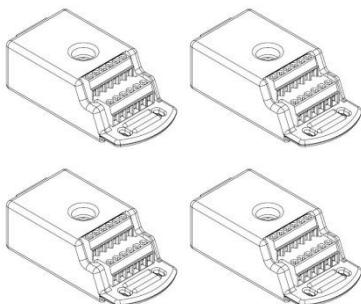
Resistor tolerance (at 25 °C) 0.1% max

Resistor power 0.25 W max



Do not connect an RJ45 plug to an RJ50 jack. Using RJ45 plugs can cause permanent damage to RJ50 pins 1 and 10, thus disabling shunt calibration.

RJ50 12-Pin Screw Terminal Accessory (CN-268)



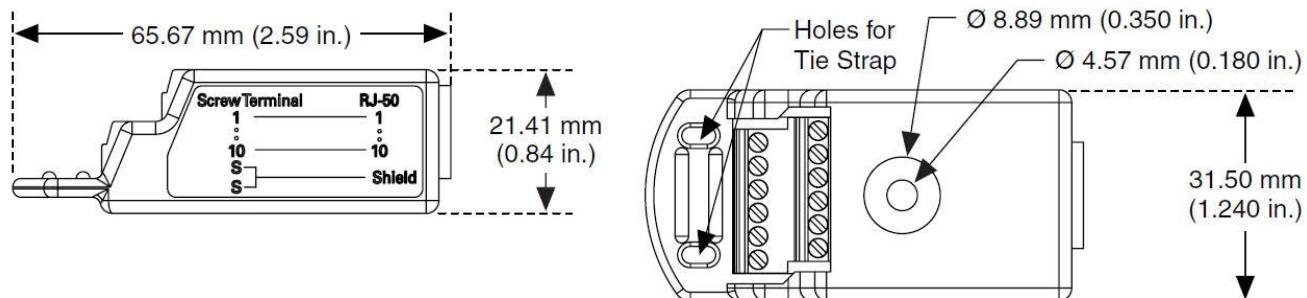
This accessory is used for Half-Bridge or Full-Bridge completion. Because bridge completion is built into the 6224, you will only need connectivity accessories.

The CN-268 is a set of four female RJ50 to 12-pin screw terminal adapters. You will need an RJ50 M/M cable to use a CN-268 component with an 6224.

Measurement Computing offers a pack of four RJ50 M/M, 1 meter (3.28ft) cables (see following *RJ50 Cables* section).

As indicated in the right-hand figure below, CN-269 and CN-270 components each have two holes that can be used to loop a plastic tie-strap through, as a means of adding strain relief for the wire connections to the screw terminals.

If you want to mount a CN-268 component, use an M4x20 screw (or similar hardware) that can fit into the 8.89 mm (0.350 in.) outer clearance/4.57 mm (0.180 in.) inner clearance hole. See figure.



Specifications:

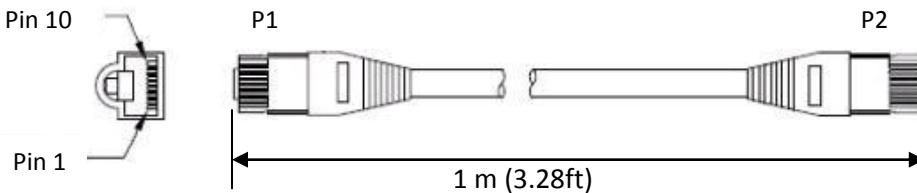
Weight 43 g (1.5oz)
Operating temperature -40 to 70 °C



Do not connect an RJ45 plug to an RJ50 jack. Using RJ45 plugs can cause permanent damage to RJ50 pins 1 and 10, thus disabling shunt calibration.

RJ50 Cables (CA-272-01)

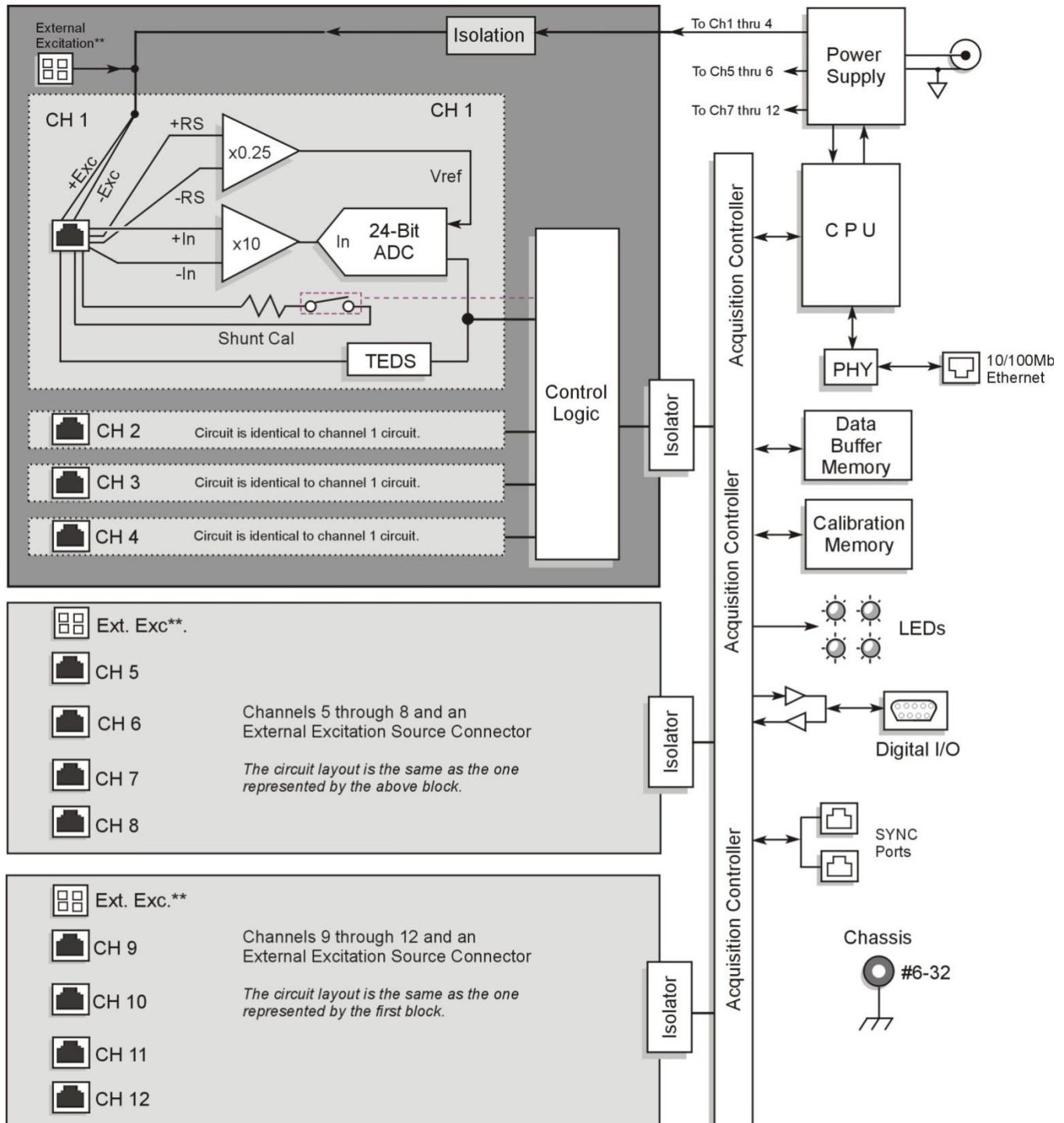
When connecting a cable from an 6224 RJ50 jack to an associated Measurement Computing accessory (CN-268, CN-269, or CN-270), be sure to only use RJ50 M/M cables. Use of another cable type can damage RJ50 pins.



The CA-272-01 includes four RJ50 to RJ50 M/M, 1 meter (3.28ft) cables.

Block Diagram

2



** Note: There are three External Excitation Voltage Source Connectors.

The first serves channels 1 through 4.

The second serves channels 5 through 8.

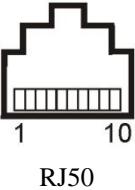
The third serves channels 9 through 12.

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Strain Channels, RJ50 Pinout

The twelve RJ50 (10p10c) jacks each have 10 pins with signal designations as indicated in the following table.

RJ50 (10p10c) Modular Plug and Jack Pinout

	Pin #	Signal Name	Signal Description
 RJ50 <i>Front View</i>	1	SC	Shunt Calibration
	2	AI+	Positive Input Signal
	3	AI-	Negative Input Signal
	4	RS+	Positive Remote Sense Signal
	5	RS-	Negative Remote Sense Signal
	6	EX+	Positive Excitation Signal (Note 1)
	7	EX-	Negative Excitation Signal (Note 1)
	8	T+	TEDS DATA (Note 2)
	9	T-	TEDS Return (Notes 1 & 2)
	10	SC	Shunt Calibration

Note 1: The three channel blocks each share three signals [within their block], as follows:

- For CH1, CH2, CH3, and CH4, the signal values of pins 6, 7, and 9 are shared.
- For CH5, CH6, CH7, and CH8, the signal values of pins 6, 7, and 9 are shared.
- For CH9, CH10, CH11, and CH12, the signal values of pins 6, 7, and 9 are shared.

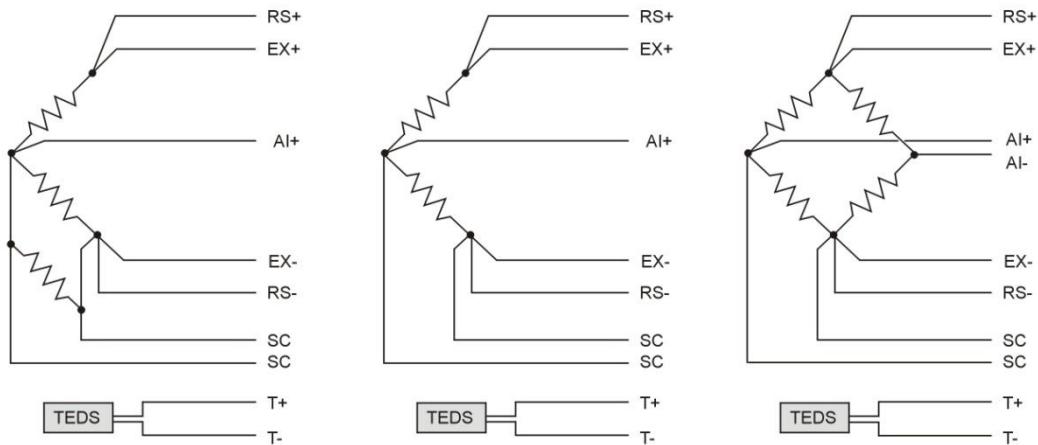
Note 2: The 6224 only supports TEDS if the acquisition software being used supports TEDS.



Do not connect an RJ45 plug to an RJ50 jack. Using RJ45 plugs can cause permanent damage to RJ50 pins 1 and 10, thus disabling shunt calibration.

Bridge Connections

The following figures indicate how to connect bridges to an the 6224. The manner in which these signals correspond to the RJ50 connector is shown on the preceding page.



Quarter-Bridge

Half-Bridge

Full-Bridge

Notes:

- (1) When connecting a bridge to the 6224, the following connections are optional: RS+, RS-, SC, T+, T-.
- (2) For the half-bridge and quarter-bridge, there is no AI- signal to connect.
- (3) To create a quarter-bridge, place an external resistor across the two SC lines of a half-bridge. Measurement Computing offers two external Quarter-Bridge accessories, CN-269 (120 ohm) and CN-270 (350 ohm). See chapter 1 for additional information regarding these accessories.
- (4) Chapter 7 contains additional bridge information, including diagrams of the various bridge types that can be selected in Encore and whether they apply to *axial* and/or *bending* strain.

Connecting TEDS Channels

Before connecting TEDS, be sure that your software supports TEDS. If it does, when connecting TEDS ensure that **neither** TEDS data (T+) nor TEDS return (T-) is tied in common to any AI signals on the 6224. See preceding schematics.

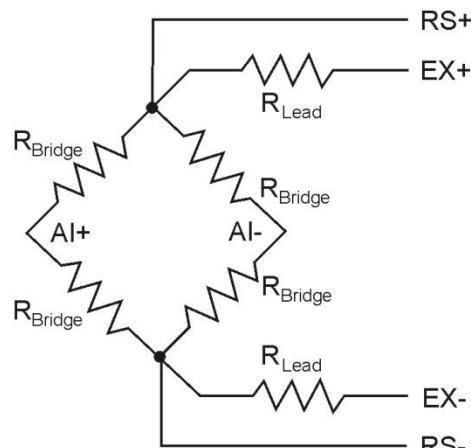
Remote Sensing

Wire resistance can create errors in bridge circuits. The 6224 can correct for these errors using two mechanisms: (1) Remote Sensing and (2) Shunt Calibration.

Remote sensing continuously and automatically corrects for errors in excitation leads, and generally is most appropriate for full- and half-bridge sensors.

Long wire and smaller gauge wire have greater resistance, which can result in gain error. The voltage drop caused by wire resistance in the wires, which connect the excitation voltage to the bridge, is a source of gain error. The 6224 includes remote sensing to compensate for this error.

Remote sense (RS) wires are connected to the point where the excitation voltage wires connect to the bridge circuit, as seen in the figure.



In the preceding figure, the *actual* bridge excitation voltage is smaller than the voltage at the EX+ and EX– leads.

If remote sensing of the actual bridge voltage is not used, the resulting gain error is as follows:

$$\text{Error in Full-bridge sensors} = 2R_{\text{Lead}}/R_{\text{Bridge}}$$

$$\text{Error in Half-bridge sensors} = R_{\text{Lead}}/R_{\text{Bridge}}$$

If the remote sense (RS) signals are connected directly to the bridge resistors, then the 6224 senses the actual bridge voltage sense and eliminates the gain errors caused by the resistance of the EX+ and EX– leads.

Shunt Calibration

The second mechanism [aside from remote sensing] used to correct errors from wire resistance is Shunt Calibration. This involves simulating the input of strain by changing the resistance of an arm in the bridge. This is accomplished by shunting, or connecting, a large resistor of known value across one arm of the bridge, creating a known strain-induced change in resistance. The output of the bridge can then be measured and compared to the expected voltage value. The results are used to correct gain errors in the entire measurement path, or to simply verify general operation to gain confidence in the setup.

Shunt calibration can be used to correct for errors from the resistance of both the excitation wiring and wiring in the individual resistors of the bridge. Shunt calibration is most critical when measurements are made on Quarter-Bridge sensors because there is no means to remotely sense around any IR drops in the connection wiring.

The 6224 includes a precision $100\text{k}\Omega$ resistor and a software-controlled switch *for each channel*. You can leave the shunt calibration terminals connected to the sensor, and then apply or remove the shunt calibration resistance in software.

While remote sensing corrects for resistances from the EX terminals on the 6224 to the sensor, shunt calibration corrects for these errors and for errors caused by wire resistance within an arm of the bridge.

A stable signal, which is typically the unloaded state of the sensor, is used first with the shunt calibration switch OFF, and then again with the switch ON. The difference in these two measurements provides an indication of the gain errors from wiring resistances and corrections for offset errors.

Internal Excitation Voltage Sources

The 6224 houses three internal voltage sources; each serves 4 channels. The first source applies excitation voltage to CH1 through CH4, the second to CH5 through CH8, and the third to CH9 through CH12.

The sensor industry does not recognize a single standard excitation voltage level. However, excitation voltage levels residing in the range of 2.5V to 10 V are common. Encore's selections for internal excitation are 2.5V, 3.3V, 5V, and 10V, and each of the three internal voltage sources can provide up to 150 mW of excitation power. The 6224 automatically reduces internal excitation voltages, as needed, to stay below 150mW.

Since channels are associated by groups of four, the excitation setting applied to one channel in a group will also be applied to the other channels in that group. As an example: if channel 1 is set to have an internal excitation of 3.3V, then channels, 2, 3, and 4 will also have 3.3V excitation.

The 6224 measures the ratio of bridge output to bridge excitation, and as such does not require accurate excitation voltage. For this reason the excitation voltage is not precisely regulated and may vary as much as 10% from the requested voltage, while still achieving accurate measurements.

The power consumed by a single bridge is V_{ex}^2/R

Where V_{ex} is the excitation voltage and R is the total resistance of the bridge.

For a full bridge, R is equal to the resistance of each element. For a half or quarter bridge, R is equal to two times the resistance of each element.

For each of the three voltage sources, the 150 mW limit allows you to power full and half bridges as follows:

- Four 350 Ω half bridges at 5.0 V, or
- Four 350 Ω full bridges at 3.3 V, or
- Four 120 Ω half bridges at 2.5 V

If you need an excitation voltage greater than 150 mW, use the four-position external excitation voltage connectors (see following section). Each of the three external connectors can be used to provide external excitation to four channels of the 6224; thus all twelve channels can receive external excitation.

External Excitation Voltage Sources

The 6224 front panel includes three 4-pin connectors which provide a means of connecting external excitation voltage sources.

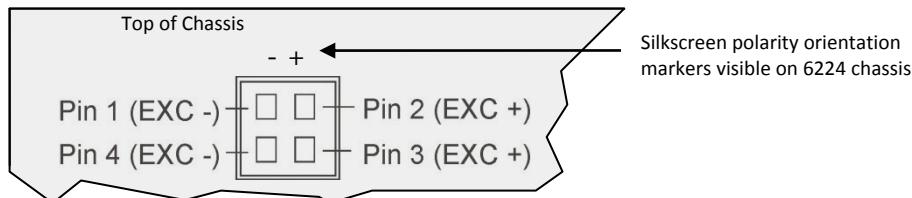
Each external voltage source serves 4 channels, as follows; the first source applies excitation voltage to CH1 through CH4, the second to CH5 through CH8, and the third to CH9 through CH12. Since channels are associated by groups of four, what you set for one channel (in a group) will also be applied to other channels of that group. Example: if you set channel 1 for 10V external excitation, channels, 2, 3, and 4 will also have 10V external excitation.

The sensor industry does not recognize a single standard excitation voltage level. However, excitation voltage levels residing in the range of 2.5V to 10 V are common.



Unless you supply external excitation voltage, we recommend that you set the excitation voltage to a value that keeps the total power below 150 mW.

The pinout and manufacturing information for the external excitation voltage source connector follows. Contact Measurement Computing for more information.



Manufacturer Information

Molex Mating Connector
4-position housing (43025-0400)
Crimp terminal (43030-0007)

Also see the preceding section, *Internal Excitation Voltage Sources*.

Mounting and Securing Connections

For a strain measurement system "mechanical noise" should also be a consideration. Movement in the connection system could translate to errors in the measurement.

Care should be taken to ensure the 6224, RJ50 cables, and dongles are physically secured to prevent relative movement.

Where to Find Additional Information

For detailed information, refer to the applicable software documentation, including software help files. Note that the Encore software includes both a *Context-sensitive Help* and access to a *Comprehensive Help* document.

In addition to software documentation, information regarding aliasing, anti-aliasing, sensors, accelerometers, sound and vibration, and transducers may prove useful to your application. The internet is a great source for this material.

In regard to TEDS (Transducer Electronic Data Sheet), you may find the IEEE 1451 standard to be of interest.

The 6224 has four 32-bit counter inputs that accept frequency inputs up to 20 MHz. The counter inputs are individually configurable for counter or encoder measurements.

You activate each input, enable logging, and configure counter options with Encore.

Counter Settings

Counter Source	The source to use for the counter. Choices are: <ul style="list-style-type: none">▪ <i>Internal Clock</i>▪ <i>Timer 1</i>▪ <i>Timer 2</i>▪ <i>Digital Line 0 – Digital Line 7</i> One source can be used in multiple counters.
Counter Gate	The gate to use for the counter. Choices are: <ul style="list-style-type: none">▪ <i>Unused</i> (do not gate the counter)▪ <i>Internal Clock</i>▪ <i>Timer 1</i>▪ <i>Timer 2</i>▪ <i>Digital Line 0 – Digital Line 7</i> One gate can be used in multiple counters.
Count Settings	The functions or values for the counter source. Choices are: <ul style="list-style-type: none">▪ <i>Clear on Read</i> – The counter counts up and is cleared after each read. By default, the counter counts up and only clears the counter at the start of a new scan command. The value of the counter before it is cleared is latched and returned.▪ <i>Totalize</i> – The counter counts up and is cleared at the start of a new scan.▪ <i>Start Count value</i> – The value used to start counting. The default is <i>zero</i>.▪ <i>Stop Count value</i> – The value used to stop counting. The default is <i>65535</i>.▪ <i>Rollover</i> – The count rolls over upon reaching the start or stop value.
Counter Source Direction	The direction in which to count. Choices are: <ul style="list-style-type: none">▪ <i>Increment</i> – Count up (default).▪ <i>Decrement</i> – Count down.
Counter Source Detection	The count to detect in relation to the signal edge. Choices are: <ul style="list-style-type: none">▪ <i>Rising Edge</i> – Detects the count when the signal goes from low to high.▪ <i>Falling Edge</i> – Detects the count when the signal goes from high to low.

Encoder Settings

Resolution	The encoder resolution, which is the number of full quadrature cycles per full shaft revolution (360 mechanical degrees). Choices are: <ul style="list-style-type: none">▪ <i>X1</i> – One count per cycle (default)▪ <i>X2</i> – Two counts per cycle▪ <i>X4</i> – Four counts per cycle
Encoder Sources	There are three encoder sources – <i>A</i> , <i>B</i> , or <i>Z</i> . For each source select one of the digital pins (<i>Digital Line 0</i> – <i>Digital Line 7</i>)



When set for Encoder measurements, the device can count "negative" values; that is, when counting down, the encoder will continue counting down below 0. This capability is useful when calculating the position of an encoder.

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Overview



CE compliant products bear the “CE” mark and include a *Declaration of Conformity* stating the particular specifications and conditions that apply. The test records and supporting documentation that validate the compliance are kept on file at the factory.

The standards are published in the *Official Journal of European Union* under direction of CENELEC (*European Committee for Electrotechnical Standardization*). The specific standards relevant to data acquisition equipment are listed on the product’s *Declaration of Conformity*.

This product meets the essential requirements of applicable European directives, as amended for CE markings in accordance with the product family standard for:

- electrical equipment for measurement, control, and laboratory use
- immunity requirements for equipment used in controlled EM environments

Refer to this product’s Declaration of Conformity (DoC) for any additional regulatory compliance information. You can view our Declarations of Conformity at www.mccdaq.com/legal.aspx (CE Information page).

Safety Conditions

Users must comply with all relevant safety conditions as stated in the user’s manual and in the pertinent *Declarations of Conformity*. Both the documentation and the associated hardware make use of the following Warning and Caution symbols. If you see any of these symbols on a product or in a document, carefully read the related information and be alert to the possibility of personal injury and/or equipment damage.



This WARNING symbol is used in documentation and/or on hardware to warn of possible injury or death from electrical shock under noted conditions.



This WARNING/CAUTION symbol is used to warn of possible personal injury or equipment damage under noted conditions.



This CAUTION symbol warns of possible equipment damage due to electrostatic discharge. The discharge of static electricity can damage some electronic components. Semiconductor devices are especially susceptible to ESD damage. You should always handle components carefully, and you should never touch connector pins or circuit components unless you are following ESD guidelines in an appropriate ESD-controlled area. Such guidelines include the use of properly grounded mats and wrist straps, ESD bags and cartons, and related procedures.



Unless otherwise stated our data acquisition products contain no user-serviceable parts. Only qualified personnel are to provide service to the devices.

The specific safety conditions for CE compliance vary by product; but general safety conditions include the following bulleted items:

- The operator must observe all safety cautions and operating conditions specified in the documentation for all hardware used.
- The host computer and all connected equipment must be CE compliant.
- All power must be off to the device and externally connected equipment before internal access to the device is permitted.
- Ensure that isolation voltage ratings do not exceed documented voltage limits for power and signal inputs. All wire insulation and terminal blocks in the system must be rated for the isolation voltage in use. Voltages above 30 Vrms or ± 60 VDC must not be applied if any condensation has formed on the device.
- Current and power use must not exceed specifications. Do not defeat fuses or other over-current protection.

Emissions/Immunity Conditions

The specific immunity conditions for CE compliance vary by product. General immunity conditions include the following:

- Cables must be shielded, braid-type with metal-shelled connectors. Input terminal connections are to be made with shielded wire. The shield should be connected to the chassis ground with the hardware provided.
- The host computer must be properly grounded.
- In low-level analog applications some inaccuracy is to be expected when I/O leads are exposed to RF fields or transients, as noted on the *Declaration of Conformity*, if applicable to the device.

CE Rules of Thumb

The device is CE Compliant at the time it leaves the factory and should remain in compliance as long as the conditions stated on the *Declaration of Conformity* continue to be met.

A few general rules of thumb:

- Use short cables.
- When assembling or disassembling components, take ESD precautions, including the use of grounded wrist straps.
- Ensure that the host computer is CE Compliant.
- Review the most recent *Declaration of Conformity*.
- Ensure all system components are properly grounded.

Noise Considerations

Controlling electrical noise is imperative because it can present problems even with the best measurement equipment. Most laboratory and industrial environments suffer from multiple sources of electrical noise. For example, AC power lines, heavy equipment (particularly if turned on and off frequently), local radio stations, and electronic equipment can create noise in a multitude of frequency ranges.

Local radio stations are a source of high frequency noise, while computers and other electronic equipment can create noise in all frequency ranges. Creating a completely noise-free environment for test and measurement is seldom practical. Fortunately, simple techniques such as using shielded/twisted pair wires, filtering, and differential voltage measurement are available for controlling the noise in our measurements. Some techniques prevent noise from entering the system; other techniques remove noise from the signal.

While many techniques for controlling noise in signals provide a means of removing the noise that is already present, the preferred solution is to prevent the occurrence of noise in the signal in the first place.

The following practices, some of which are required for CE compliance, should be employed to minimize noise.

- **Make a solid earth ground connection.** Using insulated, low resistance wire, connect the chassis to solid earth ground. This practice accomplishes the following:
 - (a) keeps radiated emissions low by keeping the chassis electrically quiet,
 - (b) keeps potential common-mode voltages low,
 - (c) improves user safety, and
 - (d) provides a safe path for Electrostatic Discharge energy back to earth ground.
- **Minimize ambient EMI.** The lower the ambient EMI, the better. Sources of electromagnetic interference include solenoids, motors, computer equipment, high power distribution wiring, etc.
- **Distance cables.** Route signal cables away from Ethernet lines, Mains and other high voltage cables and equipment to minimize signal interference from radiated noise.

Encore is the premier *Out-of-the-Box* data acquisition software package and is included with each 6000 Series module. Encore combines ease of use with advanced functionality, including customizable data layouts, powerful analysis, and reporting capabilities. Instead of having a program to log data, another to analyze, and a third to develop report data, Encore includes the functionality of all three into one package, thus shortening the learning curve, and saving time and cost.

Features

- Easily configure 6000 Series hardware
- Data streaming & playback
- Comprehensive report generation
- Drag and drop directly into Excel®
- Built-in analysis including FFT

We recommend that you watch the Encore *Quick Start Video Tutorial* prior to using Encore. After watching the video you should be able to set up and run an application. You can use Encore's *Comprehensive Help* to view details about various aspects of the application. *Comprehensive Help* includes a search function, allowing you to quickly look up the subject of interest.

Once you have installed Encore you can navigate from the host PC's Windows' Desktop to access the *Comprehensive Help* and several other items as indicated in the table below.

Use this Path from the Desktop:	To Access:	File Format
Start>>All Programs>>IOtech>>Encore>>	Comprehensive Help Encore Getting Started with Encore Quick Start Video Tutorial Readme	.chm <i>software application</i> .pdf .wmv .html
Start>>All Programs>>IOtech>>6000 Series>>	All 6000 Series user's manuals	.pdf

Should you have questions or need support you can contact Measurement Computing through one of the means provided on the front cover of this manual.

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Pressure/Force 7-10

Introduction

The 6224's channels can be set to measure strain or pressure/force. This chapter provides schematics of bridge circuits applicable to the 6224.

Strain Gauge Types Explained

This section uses figures to represent axial and/or bending strain to indicate the type(s) of strain that applies to a given bridge type. It also provides simple schematics. For each type of bridge, supplemental information shows two equations: the first is the equation used to convert voltage to strain; the second is an equation you can use to simulate the effect on strain by applying a shunt resistor across R3. In the upcoming figures and equations, acronyms, formulas, and variables are defined as:

ϵ is the measured strain (+ ϵ is tensile strain and - ϵ is compressive strain).

ϵ_s is the simulated strain.

GF is the Gauge Factor, which should be specified by the gauge manufacturer.

R_g is the nominal gauge resistance, which should be specified by the gauge manufacturer.

R_L is the lead resistance. If lead lengths are long, R_L can significantly impact measurement accuracy.

R_s is the shunt calibration resistor value.

U is the ratio of expected signal voltage to excitation voltage with the shunt calibration circuit engaged. Parameter U appears in the equations for simulated strain and is defined by the following equation:

$$U = \frac{-R_g}{4R_s + 2R_g}$$

ν is the Poisson's ratio, defined as the negative ratio of transverse strain to axial strain (longitudinal) strain.

V_{CH} is the measured signal's voltage.

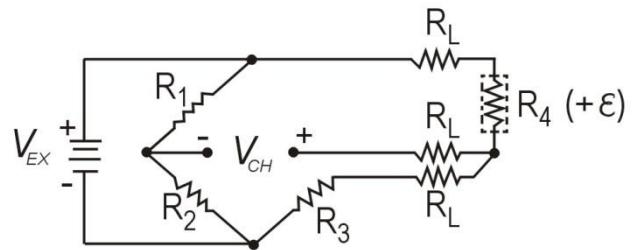
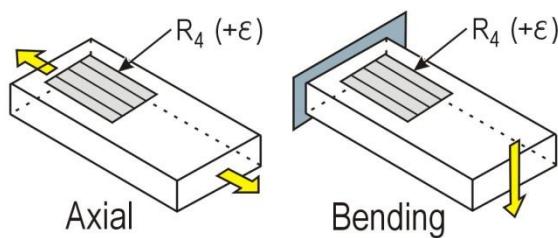
V_{EX} is the excitation voltage.

V_r is the voltage ratio that is used in the voltage to strain conversion equations and is defined by the following equation:

$$V_r = \left(\frac{V_{CH}(\text{strained}) - V_{CH}(\text{unstrained})}{V_{EX}} \right)$$

Quarter-Bridge I

Quarter-bridge type I measures either *axial* or *bending* strain.



Quarter-bridge type I has the following characteristics:

- A single active strain-gauge element is mounted in the principle direction of axial or bending strain.
- A passive quarter-bridge completion resistor (dummy resistor) is required in addition to half-bridge completion.
- Temperature variation in specimen decreases the accuracy of the measurements.
- Sensitivity at 1000 $\mu\epsilon$ is $\sim 0.5 \text{ mV}_{\text{out}} / V_{\text{Ex}}$ input.

The following symbols apply to the above circuit diagram and to the equations provided in the supplemental information.

- R1 and R2 are the half-bridge completion resistors.
- R3 is the quarter-bridge completion resistor (dummy resistor).
- R4 is the active strain-gauge element measuring tensile strain ($+\epsilon$).

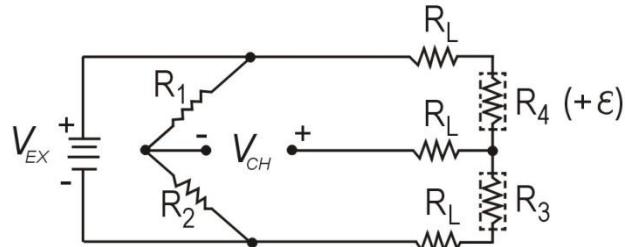
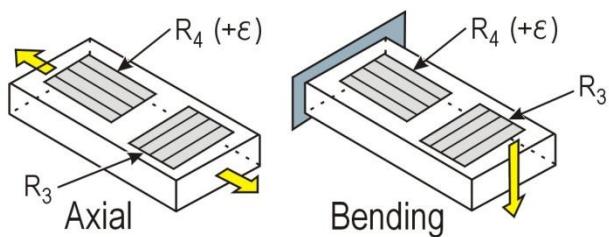
Supplemental Information

Data from strain channels (Quarter-Bridge I) is converted to strain units using the following equation:

$$\mu\epsilon = 10^6 \left[\frac{-4V_r}{GF(1 + 2V_r)} \cdot \left(1 + \frac{R_L}{R_g} \right) \right]$$

Quarter-Bridge II

Quarter-bridge type II measures either *axial* or *bending* strain.



Quarter-bridge type II has the following characteristics:

- One active strain-gauge element and one passive, temperature-sensing quarter-bridge element (dummy gauge). The active element is mounted in the direction of axial or bending strain. The dummy gauge is mounted in close thermal contact with the strain specimen but not bonded to the specimen, and is usually mounted transverse (perpendicular) to the principle axis of strain.
- This configuration is often confused with the half-bridge type I configuration, with the difference being that in the half-bridge type I configuration the R3 element is active and bonded to the strain specimen to measure the effect of Poisson's ratio.
- Completion resistors provide half bridge completion.
- Compensates for temperature.
- Sensitivity at 1000 $\mu\epsilon$ is $\sim 0.5 \text{ mV}_{\text{out}} / V_{\text{Ex}}$ input.

The following symbols apply to the above circuit diagram and to the equations provided in the supplemental information.

- R1 and R2 are half-bridge completion resistors.
- R3 is the quarter-bridge temperature-sensing element (dummy gauge).
- R4 is the active strain-gauge element measuring tensile strain ($+ \epsilon$).

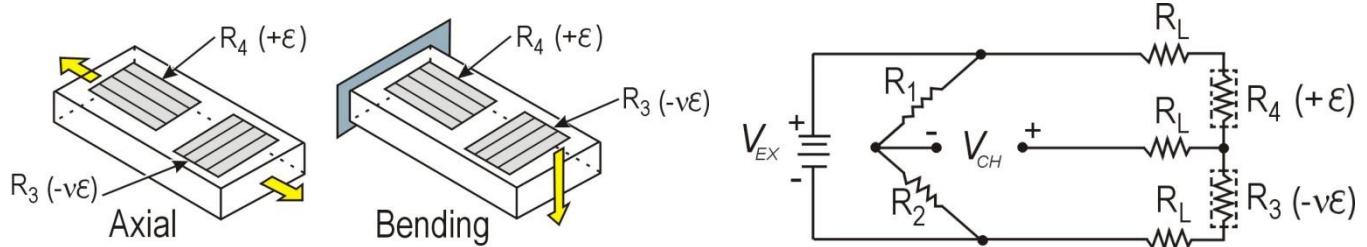
Supplemental Information

Data from strain channels (Quarter-Bridge II) is converted to strain units using the following equation:

$$\mu\epsilon = 10^6 \cdot \left[\frac{-4 \cdot V_r}{GF(1 + 2 \cdot V_r)} \cdot \left(1 + \frac{R_L}{R_g} \right) \right]$$

Half-Bridge I

Half-bridge type I measures either *axial* or *bending* strain.



Half-bridge type I has the following characteristics:

- Two active strain-gauge elements. One is mounted in the direction of axial strain, the other acts as a Poisson gauge and is mounted transverse (perpendicular) to the principal axis of strain.
- Completion resistors provide half bridge completion.
- Sensitive to both axial and bending strain.
- Compensates for temperature.
- Compensates for the aggregate effect on the principle strain measurement due to the Poisson's ratio of the specimen material.
- Sensitivity at 1000 με is ~ 0.65 mV_{out}/ V_{EX} input.

The following apply to the above circuit diagram and to the equations provided in the supplemental information.

- R1 and R2 are half-bridge completion resistors.
- R3 is the active strain-gauge element measuring compression from Poisson effect (-νε).
- R4 is the active strain-gauge element measuring tensile strain (+ε).

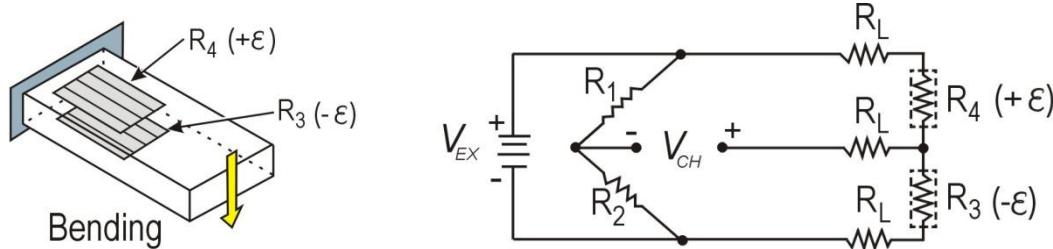
Supplemental Information

Data from strain channels (Half-Bridge I) is converted to strain units using the following equation:

$$\mu\epsilon = 10^6 \left[\frac{-4V_r}{GF[(1+\nu) - 2V_r(\nu-1)]} \cdot \left(1 + \frac{R_L}{R_g} \right) \right]$$

Half-Bridge II

Half-bridge type II only measures *bending* strain.



Half-bridge type II has the following characteristics:

- Two active strain-gauge elements. One is mounted in the direction of bending strain on one side of the strain specimen (top), the other is mounted in the direction of bending strain on the opposite side (bottom).
- Completion resistors provide half bridge completion.
- Sensitive to bending strain.
- Rejects axial strain.
- Compensates for temperature.
- Sensitivity at $1000 \mu\varepsilon$ is $\sim 1 \text{ mV}_{\text{out}} / V_{\text{EX}}$ input.

The following symbols apply to the above circuit diagram and to the equations provided in the supplemental information.

- R_1 and R_2 are half-bridge completion resistors.
- R_3 is the active strain-gauge element measuring compressive strain ($-\varepsilon$).
- R_4 is the active strain-gauge element measuring tensile strain ($+\varepsilon$).

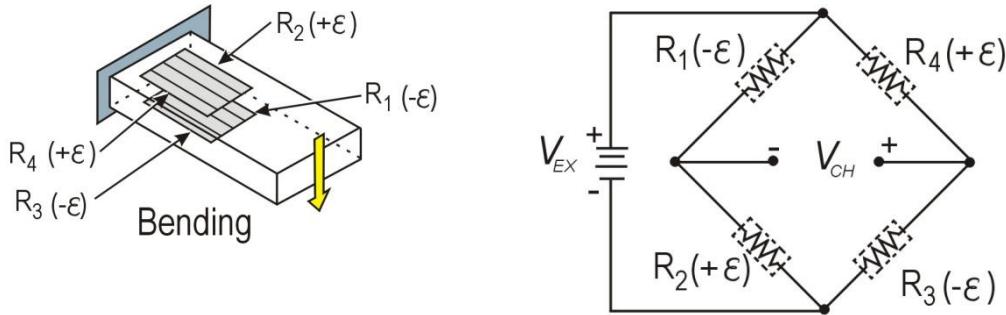
Supplemental Information

Data from strain channels (Half-Bridge II) is converted to strain units using the following equation:

$$\mu\varepsilon = 10^6 \cdot \left[\frac{-2 \cdot V_r}{GF} \cdot \left(1 + \frac{R_L}{R_g} \right) \right]$$

Full-Bridge I

The Full-bridge type I only measures *bending* strain.



Full-bridge type I configuration has the following characteristics:

- Four active strain-gauge elements. Two are mounted in the direction of bending strain on one side of the strain specimen (top), the other two are mounted in the direction of bending strain on the opposite side (bottom).
- Highly sensitive to bending strain.
- Rejects axial strain.
- Compensates for temperature.
- Compensates for lead resistance.
- Sensitivity at $1000 \mu\epsilon$ is $\sim 2.0 \text{ mV}_{\text{out}} / V_{\text{EX}}$ input.

The following symbols apply to the above circuit diagram and to the equations provided in the supplemental information.

- R1 is an active strain-gauge element measuring compressive strain ($-\epsilon$).
- R2 is an active strain-gauge element measuring tensile strain ($+\epsilon$).
- R3 is an active strain-gauge element measuring compressive strain ($-\epsilon$).
- R4 is an active strain-gauge element measuring tensile strain ($+\epsilon$).

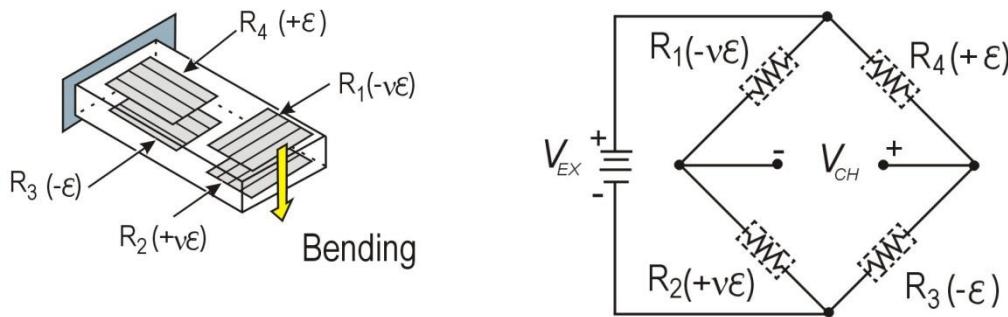
Supplemental Information

Data from strain channels (Full-Bridge I) is converted to strain units using the following equation:

$$\mu\epsilon = 10^6 \cdot \left[\frac{(-V_r)}{GF} \right]$$

Full-Bridge II

Full-bridge type II only measures bending strain.



Full-bridge type II configuration has the following characteristics:

- Four active strain-gauge elements. Two are mounted in the direction of bending strain with one on one side of the strain specimen (top), the other on the opposite side (bottom). The other two act together as a Poisson gauge and are mounted transverse (perpendicular) to the principal axis of strain with one on one side of the strain specimen (top), the other on the opposite side (bottom).
- Rejects axial strain.
- Compensates for temperature.
- Compensates for the aggregate effect on the principle strain measurement due to the Poisson's ratio of the specimen material.
- Compensates for lead resistance.
- Sensitivity at 1000 με is ~ 1.3 mV_{out}/ V_{EX} input.

The following symbols apply to the above circuit diagram and to the equations provided in the supplemental information.

- R1 is an active strain-gauge element measuring compressive Poisson effect (-vε).
- R2 is an active strain-gauge element measuring tensile Poisson effect (+vε).
- R3 is an active strain-gauge element measuring compressive strain (-ε).
- R4 is an active strain-gauge element measuring tensile strain (+ε).

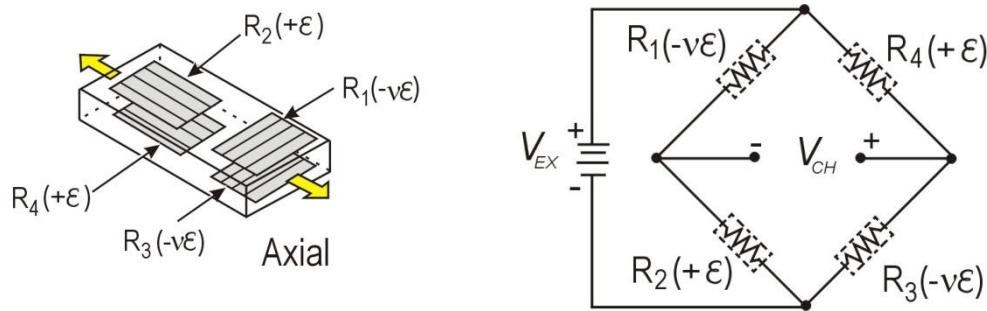
Supplemental Information

Data from strain channels (Full-Bridge II) is converted to strain units using the following equation:

$$\mu\epsilon = 10^6 \cdot \left[\frac{-2 \cdot V_r}{GF(1 + v)} \right]$$

Full-Bridge III

Full-bridge type III only measures *axial* strain.



A Full-bridge type III configuration has the following characteristics:

- Four active strain-gauge elements. Two are mounted in the direction of axial strain with one on one side of the strain specimen (top), the other on the opposite side (bottom). The other two act together as a Poisson gauge and are mounted transverse (perpendicular) to the principal axis of strain with one on one side of the strain specimen (top), the other on the opposite side (bottom).
- Compensates for temperature.
- Rejects bending strain.
- Compensates for the aggregate effect on the principle strain measurement due to the Poisson's ratio of the specimen material.
- Compensates for lead resistance.
- Sensitivity at 1000 $\mu\epsilon$ is $\sim 1.3 \text{ mV}_{\text{out}} / V_{\text{EX}}$ input.

The following symbols apply to the above circuit diagram and to the equations provided in the supplemental information.

- R1 is an active strain-gauge element measuring compressive Poisson effect ($-v\epsilon$).
- R2 is an active strain-gauge element measuring tensile strain ($+\epsilon$).
- R3 is an active strain-gauge element measuring compressive Poisson effect ($-v\epsilon$).
- R4 is an active strain-gauge element measuring the tensile strain ($+\epsilon$).

Supplemental Information

Data from strain channels (Full-Bridge III) is converted to strain units using the following equation:

$$\mu\epsilon = 10^6 \left[\frac{-2 \cdot V_r}{GF[(1 + v) - V_r(v - 1)]} \right]$$

Pressure/Force

Pressure is defined as force per unit area that a fluid exerts on its surroundings. For example, pressure, P, is a function of force, F, and area, A.

$$P = F/A$$

Data from pressure/force channels is converted using the following equation:

$$P = \left[\frac{O_{fs}}{S} \left(\frac{V_m}{V_{ex}} \right) \right]$$

Where:

P = Pressure

S = the sensitivity of the gauge in mV/V

O_{fs} = the Full Scale Output (Output_{fs})

V_m = the measured voltage

V_{ex} = the excitation voltage

Electrostatic Discharge (ESD) Handling Notice..... 8-1

Product Care 8-1

The ReadMe File and the Install CD-ROM 8-2

Customer Support 8-2

Electrostatic Discharge (ESD) Handling Notice



The discharge of static electricity can damage some electronic components. Semiconductor devices are especially susceptible to ESD damage. You should always handle components carefully, and you should never touch connector pins or circuit components unless you are following ESD guidelines in an appropriate ESD-controlled area. Such guidelines include the use of properly grounded mats and wrist straps, ESD bags and cartons, and related procedures.

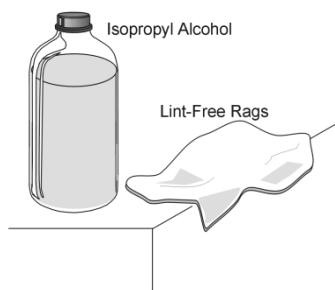
Product Care

6000 series devices are essentially maintenance free and require only a minimal amount of care. They should be treated much like any other high-tech piece of equipment. In general:

- Operate the units in ventilated and relatively dust-free environments.
- Keep the units clear of harsh chemicals and abrasive elements.
- Avoid exposing the products to extreme heat; for example, avoid setting the units near boilers and furnaces.
- Avoid extreme shock and vibration.
- Avoid subjecting the units to liquids and extremely fine air particulate, such as silica dust.
- Never open the unit. The unit should only be opened by qualified service technicians.

A “common-sense” approach to handling acquisition components will go a long way in protecting them from inadvertent damage.

Note that you can use lint-free rags and Isopropyl Alcohol (Rubbing Alcohol) to clean the outer surfaces of a 6000 series device.



The Readme File and the Install CD-ROM

The Install CD-ROM includes a ReadMe file. The ReadMe may contain late-breaking information that does not appear in other documentation. During installation you should review the ReadMe file when prompted to by the program.

The Install CD-ROM includes:

- Windows drivers
- Encore, interactive measurement software*
- User documentation in Adobe® PDF format

Customer Support

If you need to report problems or request product support . . .

Note: Please do not return any equipment to the factory unless it has an RMA number (Return Merchandise Authorization number). RMA numbers are issued by the factory.

To report problems or request support, contact our Application Engineering department. Contact information follows shortly. When you contact us, please have the following information available, as applicable:

- Hardware model numbers and software version numbers.
- Operating system, type of computer, and device information in the Windows control panel, such as interrupts and address settings for our hardware and others.
- Results of any tests.
- Hardware setup and software configuration.
- Information on input signals, including voltage ranges, signal impedance ranges, noise content, and common mode voltages.
- The name of a contact person from your company who can discuss the problems encountered.
- Instructions for return shipping.
- All troubleshooting notes and comments on tests performed, and all problem-related conditions.

Note: Before calling for assistance, take a few minutes to read all parts of the manual that may be relevant to the problem. Also, please review the troubleshooting material.

You can reach Measurement Computing by one of the following means:

Phone: **(508) 946-5100**
Fax: **(508) 946-9500**
E-mail: info@mccdaq.com
Internet: www.mccdaq.com
Mail: **Measurement Computing • 10 Commerce Way • Norton, MA 02766**

All equipment returned to the manufacturer must have an RMA (Return Material Authorization) number. You can obtain an RMA number from our Application Engineering department. When returning the equipment, use the original shipping container (or equivalent) to prevent damage. Put the RMA number on your shipping label to ensure that your shipment will be handled properly. After receiving your equipment, we will fax a confirmation form that summarizes the charges (if applicable) and expected return date.

* Encore includes a *Comprehensive Help* (.chm), a *Getting Started with Encore* manual, (.pdf) and *Quick Start Video Tutorial* (.wmv).

The following specifications are typical for the range –40 to 50°C, unless otherwise noted.

Input Characteristics

Number of analog channels	12
Bridge completion	
Full and half	Internal
Quarter.....	External
ADC resolution.....	24 bits
Type of ADC	Delta-sigma (with analog pre-filtering)
Sampling mode.....	Simultaneous
Data rates (f_s)	(50kS/s)/n, n = 1, 2, ... 31.
Multiple device, channel sync skew ¹	1 Sample Period
Single device, channel-to-channel	
matching (calibrated).....	350nS (max)
Master timebase (internal)	
Frequency	12.8 MHz
Accuracy.....	± 100 ppm max
Nominal full-scale range	± 25 mV/V
Scaling coefficient	2.9802 nV/V per LSB
Overvoltage protection between any two terminals	± 30 V

Accuracy

Measurement Conditions*	Percent of Reading	Offset
Calibrated, max (-40 to 50 °C)	0.20%	0.0625 mV/V
Calibrated, typ (25 °C, ±5 °C)	0.05%	0.0125 mV/V

* Excluding offset null or shunt calibration.

Gain drift..... 10 ppm/°C max

Offset drift

2.5 V excitation	0.6 μV/V per °C
3.3 V excitation	0.5 μV/V per °C
5 V excitation	0.3 μV/V per °C
10 V excitation	0.2 μV/V per °C

Channel-to-channel matching (calibrated)¹

Input Signal Frequency (f _{in})	Gain	
	Typical	Maximum
0 to 1 kHz	0.15%	0.3%
1 to 20 kHz	0.4%	1.1%

Phase nonlinearity

0 to 1 kHz

< 0.001°

0 to 20 kHz

± 0.1°

Input delay

4.8 μs + 38.4/f_s

¹ Refer to the synchronization section of chapter 1 for information regarding multiple devices.

Passband

Frequency $0.45 \cdot f_s$
 Flatness 0.1 dB max

Stopband

Frequency	$0.55 \cdot f_s$
Attenuation	100 dB
Alias-free bandwidth	$0.45 \cdot f_s$
Oversample rate.....	$64 \cdot f_s$
Attenuation at oversample rate ¹	
50 kS/s.....	90 dB @ 3.2 MHz
10 kS/s.....	60 dB @ 640 kHz

Common-mode voltage

All signals to earth ground ± 60 VDC

Common-mode rejection ratio (CMRR)

Relative to earth ground ²	-140 dB @ 0 to 60 Hz
Relative to EX-	-85 dB @ 0 to 1 kHz

Input noise

Excitation Voltage	Density (nV/V _{rms} per $\frac{V}{V}$)	Total (50kS/S)(μ V/V _{rms})	0 to 1 kHz (nV/V _{rms})
2.5 V	8	1.3	250
3.3 V	6	1.0	190
5.0 V	4	0.6	130
10.0 V	2	0.3	65

Spurious-free dynamic range (SFDR) 106 dB, (1KHz, -60 dBFS)

Total harmonic distortion (fundamental @ -20 dBFS)

1 kHz	-100 dB
8 kHz	-90 dB

Excitation noise 0.1 mV/V_{rms}

Crosstalk

1 kHz	-110 dB
10 kHz	-100 dB

Shunt calibration

Resistance.....	100 k Ω
Resistor accuracy	
25°C	$\pm 110 \Omega$
-40 to 50°C	$\pm 200 \Omega$

Excitation

Internal voltage.....	2.5 V, 3.3 V, 5.0 V, 10.0 V
Internal power	450 mW max
External voltage.....	2 V to 10 V

¹ Rejection by analog pre-filter of signal frequencies at oversample rate.

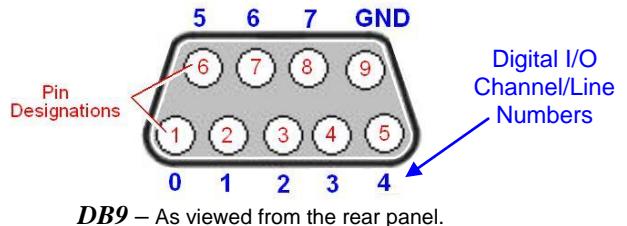
² Measured with a balanced cable. Shielded cables may be significantly unbalanced.

Digital I/O

Channels: 8 Digital I/O, programmable as a single port, or as individual lines

Power-up mode: Inputs pulled low

Connector: DB-9 female (*figure*)



Programmable Input Scanning Modes:

Asynchronous: Under program control at any time relative to analog scanning.

Synchronous: Data captured synchronously with the analog channels.

Input Levels:

Low: 0 to +0.8V

High: +2.0V to +5.0V

Input Voltage Range without Damage: -0.6V to +5.6V max

Input pull-down resistor: 10kΩ

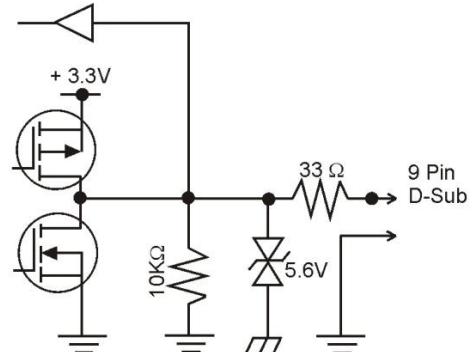
Output voltage range: 0 to +3.0V

(may be externally pulled up to 5.6V without damage)

Output resistance: 40Ω

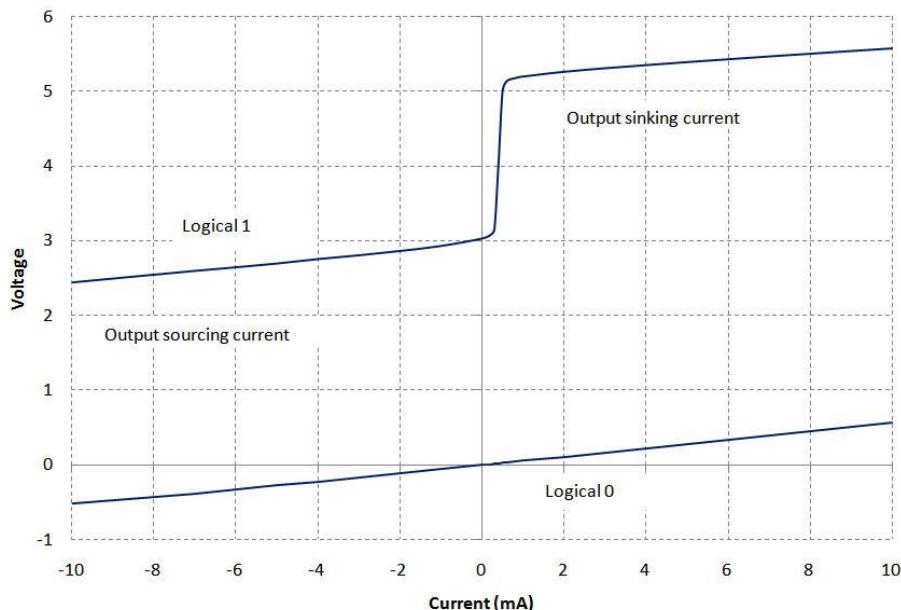
Output Levels: (see *6000 Series Digital Output* graph below)

Sampling: 1 MHz max continuous



Output timing: Outputs are always written asynchronously.

6000 Series Digital Output



Counter Input

Channels	Up to 4 independent
Resolution.....	32-bit
Input frequency.....	20 MHz maximum
Input characteristics.....	10 k Ω pull-down
Trigger level	TTL
Minimum pulse width.....	25 ns high, 25 ns low
Programmable modes	Counter, Encoder
Encoder resolution.....	x1 (default), x2, and x4
Encoder sources.....	A, B, and Z; can be assigned to any digital pin x .
Counter source.....	Internal Clock, Timer 1, Timer 2, and digital pin x . One source can be used in multiple counters.
Counter mode options.....	Totalize, Clear on Read, Rollover, Stop at the Top, Increment, Decrement, Rising Edge, Falling Edge
Counter gate options.....	Unused, Internal Clock, Timer 1, Timer 2, and Digital pin x . One gate can be used in multiple counters.

Power

Power consumption	6.3 W typ, 6.6 W max Power jack Barrel type: 5.5 mm O.D.; 2.1 mm I.D.
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Physical Characteristics

Weight	1.3 kg (2.88 lb) Dimensions 276.9mm W x 169.8mm D x 30.5mm H (10.9" W x 6.685" D x 1.2" H)
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Environmental

6224 units are intended for indoor use only but may be used outdoors if installed in a suitable enclosure.
Operating temperature..... -40 to 50°C
Storage temperature..... -40 to 75°C
Ingress protection
IP 40
Operating humidity
10 to 90% RH,
Noncondensing
5 to 95% RH, noncondensing
Maximum altitude
2,000 m (6,562 ft)
Pollution Degree.....
2

Calibration

Calibration interval	1 year
Contact Measurement Computing for information regarding calibration service.	

Note: The above calibration information pertains to hardware calibration, not to be confused with "user" or "software" calibration. When performing a "user" calibration via Encore (or other software) keep in mind that sample rate affects both gain and offset of the hardware, and therefore any "user" calibration should be performed at the same sample rate that is intended for measurements.

Accessories

TR-60U	24VDC @ 0.8A (max) universal power supply
CA-1	120V IEC AC Mains cable (US)
CA-216	220V IEC Mains Cable (EU)
CN-268	RJ50, 12 pin Screw Terminal, 4pk
CN-269	RJ50, 120 ohm Quarter Bridge, 4pk
CN-270	RJ50, 350 ohm Quarter Bridge, 4pk
CA-272-01	RJ50 to RJ50 M/M, 1 meter (3.28ft) Cable, 4pk
CA-74-1	RJ12 Shielded Cable, 6-Conductor, Sync, 0.3m (1ft) ¹
190658A-01	Stacking plate kit; includes: 2 stacking plates 8 screws (8-32x0.5in, Phillips Flat, 82 degree)
HA-210-5-BK:	Handle kit; Includes: 1 molded black plastic handle 2 screws (1/4-20x7/8in, Phillips Pan Head)
CA-192-7C	Ethernet Crossover Cable, 2.133m (7ft) ^{2,3}
CA-242	Ethernet Patch Cable, 0.457m (1.5ft) ²
CA-242-7	Ethernet Patch Cable, 2.133m (7ft) ²

Cable Notes:

¹ Up to nine units can be synchronized. The total combined length of the SYNC cables is not to exceed 2.438m (8 ft).

² Ethernet cable length must be <3 m (9.8 ft) in order for the system to be CE Compliant.

³ Ethernet crossover cables should only be used for direct network connections. In particular, attempting to connect a device to a Hub using a crossover cable may prevent that network link from functioning. Some modern routers have become an exception by including logic to detect the crossover cable and allow the network link to function.